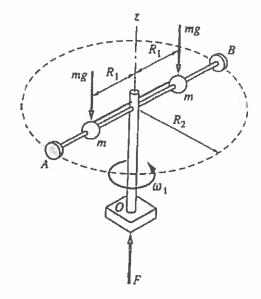
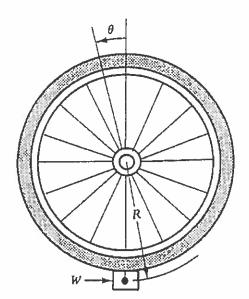
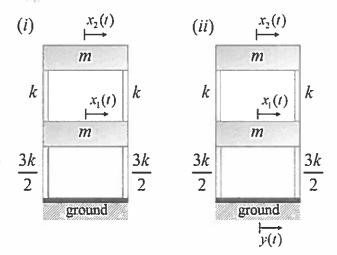
The assembly shown consists of two small balls, each of mass m, which slide on a frictionless, rigid frame OAB of negligible mass. The support at O permits free rotation of the frame about the z-axis. The frame is initially rotating with angular velocity  $\omega_1$  while strings hold the balls at a radial distance  $R_1$ . The strings are then cut simultaneously, permitting the balls to slide toward the stops at A and B. If the balls hit the stops and stay attached to the stops, determine the final angular velocity  $\omega_2$  of the assembly.



A bicycle wheel and tire are supported so that they are free to rotate about their centroidal axis through the hub of the wheel. A small weight W is glued to the tire, as shown in the figure, at a distance R from the axis of rotation. When the tire/wheel/weight assembly is displaced from the vertical by a small angle, the assembly is observed to oscillate 3 cycles every 10 seconds. If R = 0.28 m and W = 3.34 N, determine the centroidal mass moment of inertia I of the wheel and tire.



Consider the planar two-story building model shown below for (i) free and (ii) forced vibrations. Neglect damping and assume lumped-parameter behavior, i.e. assume rigid masses (m) and massless lateral stiffnesses (k). The small displacements  $x_1(t)$  and  $x_2(t)$  of the lumped masses are measured relative to the ground in both cases.



- (a) Consider free vibrations and obtain the equations of motion in matrix form.
- (b) Find the natural frequencies and mode shapes. Sketch the mode shapes.
- (c) For the configuration in part (i), derive the response to initial displacement conditions  $x_1(0) = 2\delta$ ,  $x_2(0) = -\delta$ ,  $\dot{x}_1(0) = \dot{x}_2(0) = 0$ , where  $\delta$  is a constant.
- (d) For arbitrary ground excitation (displacement) y(t) in part (ii), obtain the forced equations of motion in matrix form.
- (e) For harmonic ground excitation  $y(t) = Y_0 \sin \omega t$ , find the forced response, i.e. particular solution (you do not have to use modal analysis). Neglect the initial condition effects.

<u>Note:</u> Your results must be in terms of the given constants and variables  $(m, k, x_1(t), x_2(t),$  etc.).

Consider two identical, homogeneous, railroad wheels (with small flanges) which spin about an adjoined axle with angular speeds  $\sigma_i$  (inner wheel i) and  $\sigma_o$  (outer wheel o) relative to the axle

itself. Each wheel can be modeled as a cylinder with mass m and radius r. The axle has length l and can be considered light. The assembly is moving/turning as a whole on a horizontal, circular track with constant (inertial) angular velocity  $\Omega$ . The circular track has a center O (not labeled) located a distance R from the first railroad wheel. The wheels roll without slipping on the track. For a sufficiently high  $\Omega$  the inside wheel will lift off of the track. Find this value of  $\Omega$  in terms of g, l, r, and R.

