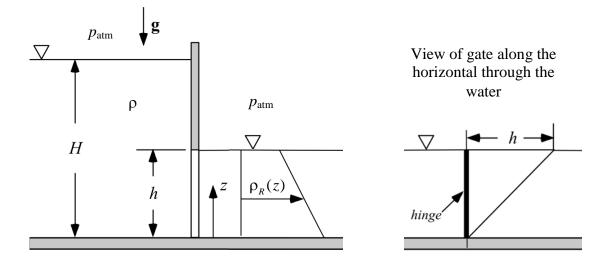
- 1) A hawk with a wing span five times larger than its prey, a sparrow, has a wing beat frequency $\omega = 1.2 \text{ s}^{-1}$. In order for the sparrow to survive, it must have a higher wing beat frequency.
 - a) Use dimensional analysis to find the relevant dimensionless groups if the wing beat frequency, ω , is a function of the wing span, *S*, the specific weight of the birds, γ (assume that the hawk and the sparrow both have the same specific weight), the acceleration due to gravity, *g*, and the density of air ρ . Then express the wing beat frequency as a function of the other relevant parameters.
 - **b**) What is the minimum wing beat frequency that the sparrow must have in order to avoid being captured by the hawk? Assume that there is a power-law relation between the wing beat frequency and wing span, so $\omega \propto S^n$.



A triangular gate of width *h* and height *h* in a vertical wall divides two bodies of water, which are both bounded above by air at atmospheric pressure p_{atm} , as sketched above (note that the view of the gate and hinge on the right is what would be seen looking from left-to-right through the water). The water on the left side of the gate is of constant density ρ and depth *H*, while that on the right side of the gate extends only to the top of the gate and is linearly density-stratified through the use of salt, having a density profile given by $\rho_R(z) = \rho + \alpha(h-z)$, where $\alpha > 0$ is a constant (so that the density of the salty water at the top of the gate on the right-hand side matches the constant density of the fresh water on the left-hand side).

- a) Determine the gage pressure distributions on both sides of the gate.
- **b**) Determine the stratification parameter α that will keep the gate in a closed position, if no other forces are present.

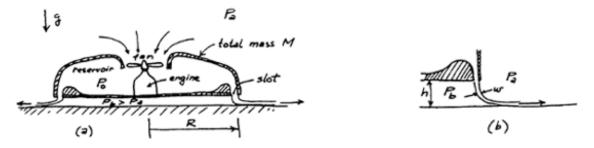


Figure (a) on the left shows the cross-section of an air cushion vehicle of the "peripheral jet" type, first developed by Christopher Cockerell in the mid-1950s. A fan draws air from the ambient atmosphere at pressure p_a through an intake of area A and compresses it to a stagnation pressure p_o in the reservoir inside the vehicle. The air then exhausts downward as a steady jet through a narrow slot of width w at the periphery of the vehicle, creating a positive gage pressure (*i.e.*, the "air cushion") under the vehicle, that allows the vehicle to float at a height h above the ground.

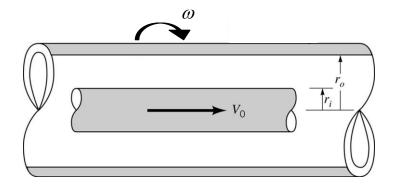
The circular vehicle has a total mass *M* and outer radius *R*. Let the pressure difference $\Delta p \equiv p_{o} - p_{a}$. Assume that $w \ll R$ and $h \ll R$, and that the flow from the reservoir to the slot is steady, incompressible and inviscid. Also assume that the pressure under the vehicle p_{b} is just slightly greater than p_{a} , so $p_{b} - p_{a} \ll \Delta p$.

The known parameters are M, g, R, w and Δp .

- a) Derive an expression for the velocity of the air across the slot jet V_j .
- **b)** Show that the weight of the vehicle $Mg = (p_b p_a)\pi R^2$. Hint: the pressure across the intake at the top of the vehicle is less than p_a when the fan is on, so you will have to show that the momentum flux is negligible compared with the net pressure force on a hemispherical control volume that encloses the vehicle.

Now consider the the operating condition for this vehicle when $h \gg w$, as shown in the expanded view of Figure (b) on the right. Here, the jet issues from the slot as a thin, sheet of constant width w which becomes parallel to the ground, and flows radially outwards along the horizontal.

- c) Obtain an expression for $p_b p_a$ in terms of the known parameters and *h*, and show that $p_b p_a \ll \Delta p$ for $h \gg w$. Then determine *h* in terms of the known parameters.
- d) The power delivered by the fan to the fluid $\dot{W} = (\Delta p)Q$, where Q is the volume flowrate through the vehicle. Show that for a given R and h, choosing a fan that delivers the power required at the lowest pressure Δp minimizes the specific power $\dot{W}/(Mg)$.



A viscous, incompressible, and Newtonian fluid fills the gap between two infinitely long, concentric cylinders. The outer cylinder has inner radius r_o and the inner cylinder has outer radius r_i . The outer cylinder rotates with a constant angular velocity ω , whereas the inner cylinder moves with a constant longitudinal velocity V_0 . Assume the flow is laminar, fully developed and axisymmetric.

- **a**) Formulate the relevant assumptions and state the appropriate boundary conditions for this problem.
- **b**) Find the velocity field in the fluid $\vec{\mathbf{V}}$.
- c) Is the pressure field p uniform in the fluid? Explain your answer.

Continuity equation

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial (r \rho v_r)}{\partial r} + \frac{1}{r} \frac{\partial (\rho v_{\theta})}{\partial \theta} + \frac{\partial (\rho v_z)}{\partial z} = 0$$

Navier-Stokes equations

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_{\theta}^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial p}{\partial r} + \rho g_r + \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rv_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_{\theta}}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right]$$

$$\rho \left(\frac{\partial v_{\theta}}{\partial t} + v_r \frac{\partial v_{\theta}}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_{\theta}}{\partial \theta} + \frac{v_r v_{\theta}}{r} + v_z \frac{\partial v_{\theta}}{\partial z} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_{\theta} + \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rv_{\theta})}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_{\theta}}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_{\theta}}{\partial z^2} \right]$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial p}{\partial z} + \rho g_z + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right]$$